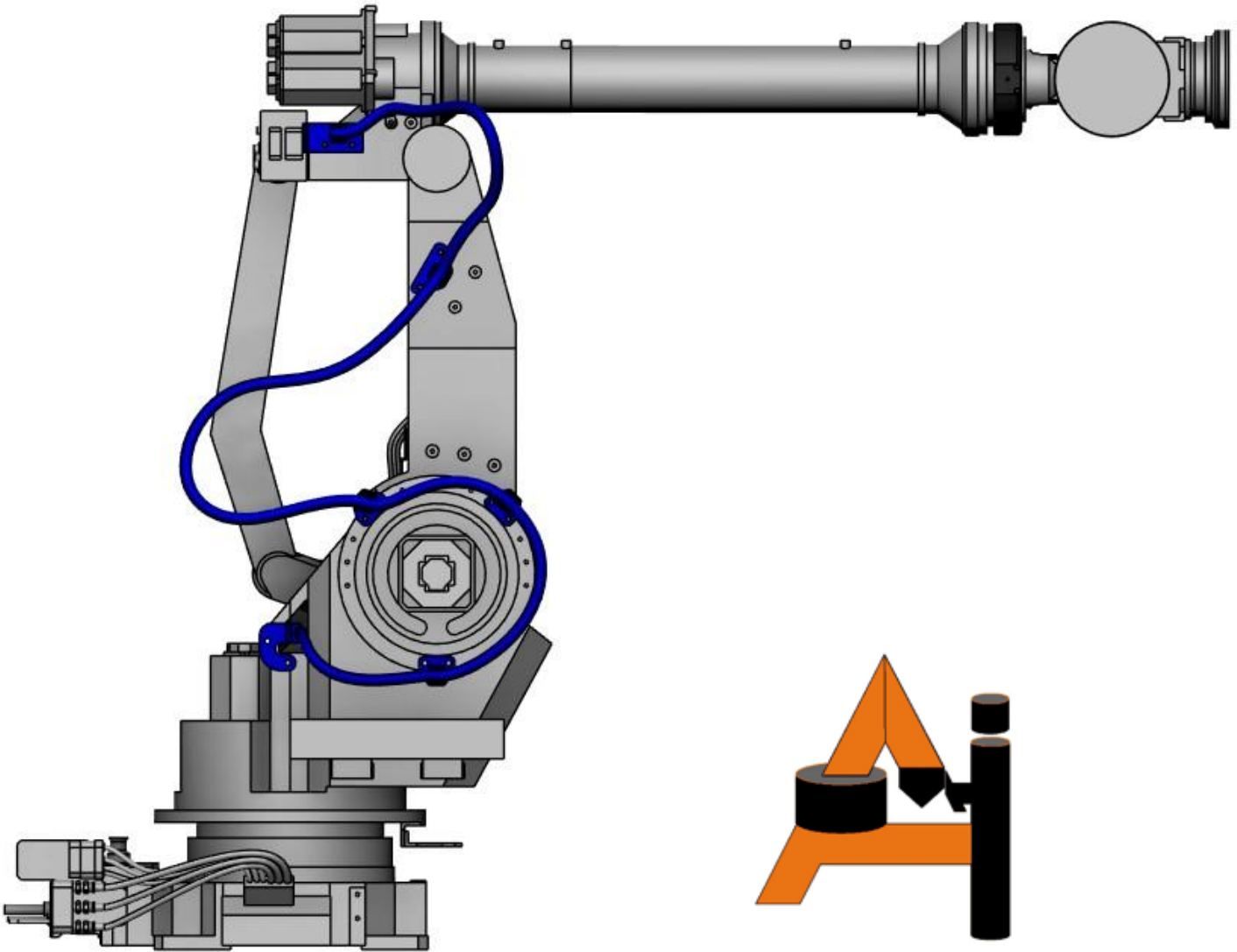


Enet Conversion Kit Manual

260L MH

#20019400-00



**Automation
Intelligence LLC**

**6181 Taylor Dr
Flint, MI 48507**

Parts Included

QTY.	PART DESCRIPTION	PART # (S)
13	PolyMade Tube 29mm, quantity in ft	R29S-13
7	Hose Clamp	CFBS-AS29-ABS-000
1	J3-1 260L MH	20030300-01
1	J1-1 260L MH	20026300-00
1	J1-2 260L MH	20027300-00
3	J2-1 260L MH	20028300-00
1	J2-2 260L MH	20029300-01
7	Velcro Buckle Strap	VS-15012050
2	M6 x 16 (2), M12 x 20 (11)	20035400-00
1	Cable tie HLDR SNGL torque mount	HDM501HIHSUVH4
1	10-Inch Heavy-Duty Self-Fastening Cable Ties	NBL-B10-100B
1	Ethernet/IP, high-flex, double-ended cord set, M12 male to male straight, 4-pin, 5m	0985 806 100/5m
2	BULKHEAD, ETHERNET, INDUSTRIAL, 4 PIN, MICRO, FEMALE-FEMALE	FKSD FKSD 44/M12
2	COVER, MICRO (M12), EXTERNAL THREADS	ZVK

On the side panel of the robot as shown in *Fig.1*.



Figure 1

Mark out a hole 38mm from the bottom of the panel and 50mm from the side of the panel. Drill out the hole to 14mm. Once drilled remove plate from robot

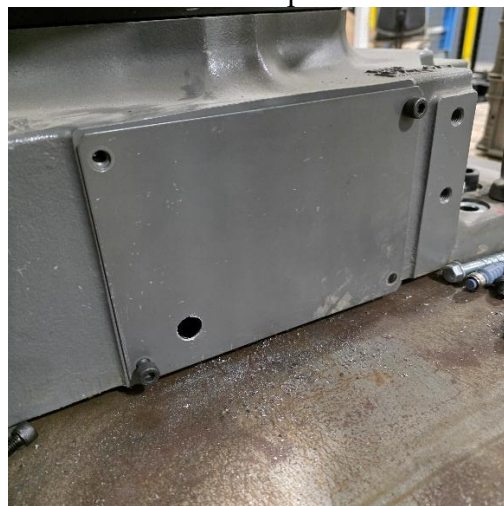


Figure 2

Insert the bulkhead and tighten it down in the drilled hole.



Figure 3

Feed wire on loose end of the kit through the grommet of the robot by loosening the velcro and attaching it to the bulkhead. Reattach the plate with the bulkhead back to the robot.



Figure 4

Mount the first bracket (20026300-00) from the loose end of the kit to the holes shown in *Fig. 5*. It should be mounted as shown in *Fig. 6*.

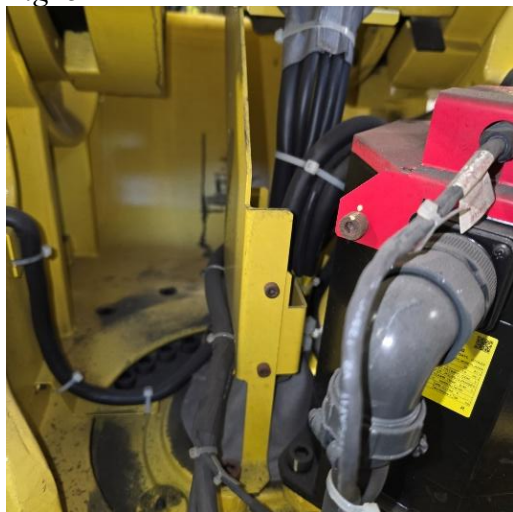


Figure 5



Figure 6

Mount the second bracket (20027300-00) to the holes shown in *Fig. 7*. It should be mounted as shown in *Fig. 8*.

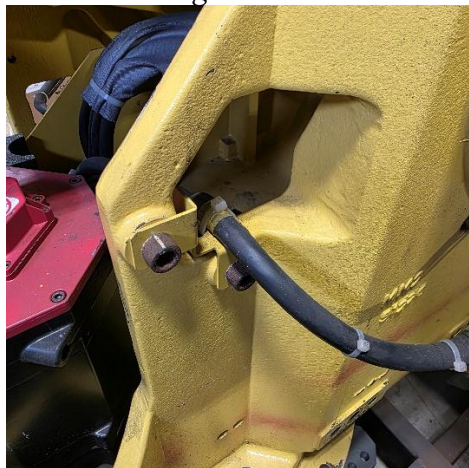


Figure 7

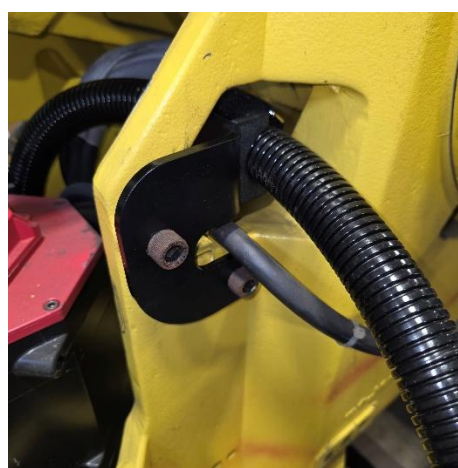


Figure 8

Mount the third bracket (20028300-00) to the holes shown in *Fig. 9*. It should be mounted as shown in *Fig. 10*.



Figure 9



Figure 10

Mount the fourth bracket (20028300-00) to the holes shown on *Fig. 11*. It should be mounted as shown on *Fig. 12*.



Figure 11



Figure 12

Mount the fifth bracket (20028300-00) to the holes shown on *Fig. 11*. It should be mounted as shown on *Fig. 12*.

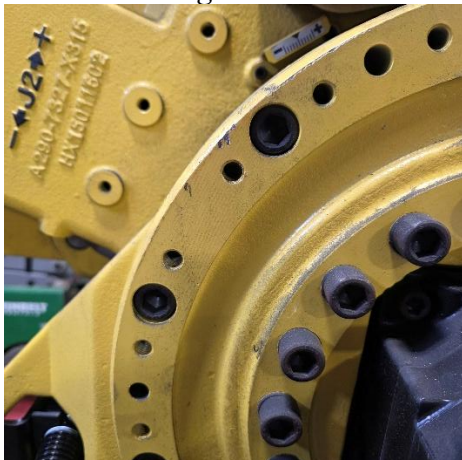


Figure 10



Figure 14

Mount the sixth bracket (20029300-01) to the holes shown on *Fig. 15*. It should be mounted as shown on *Fig. 16*.



Figure 15



Figure 16

Mount the Cable mount to the robot shown in *Fig. 17*. It should be mounted as shown on *Fig. 18*.

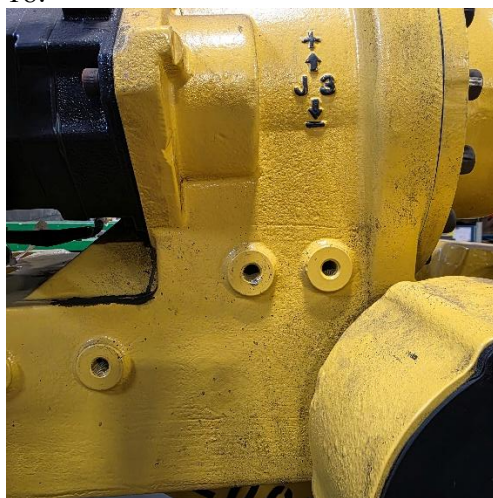


Figure 17

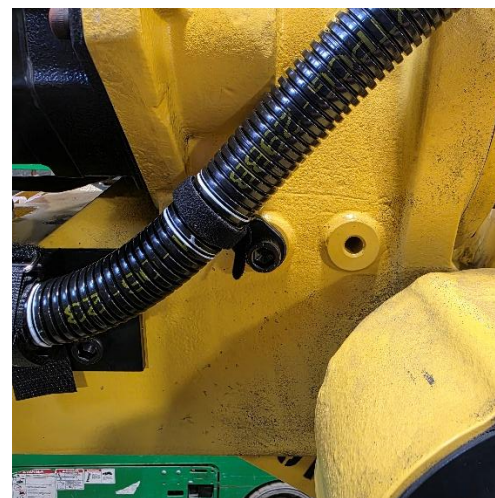


Figure 18

Mount the seventh bracket (20030300-01) to the holes shown on *Fig. 19*. It should be mounted as shown in *Fig. 20*.

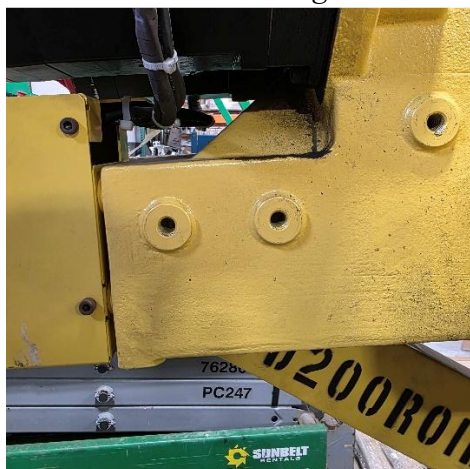


Figure 1119

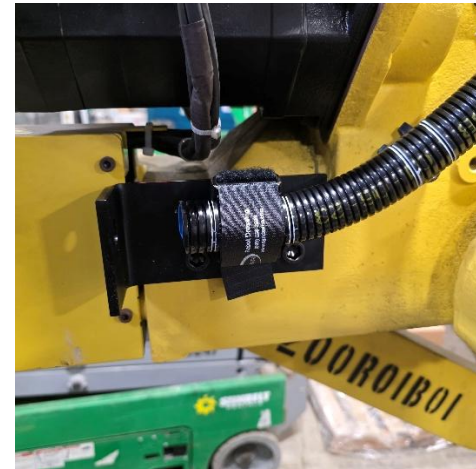


Figure 20